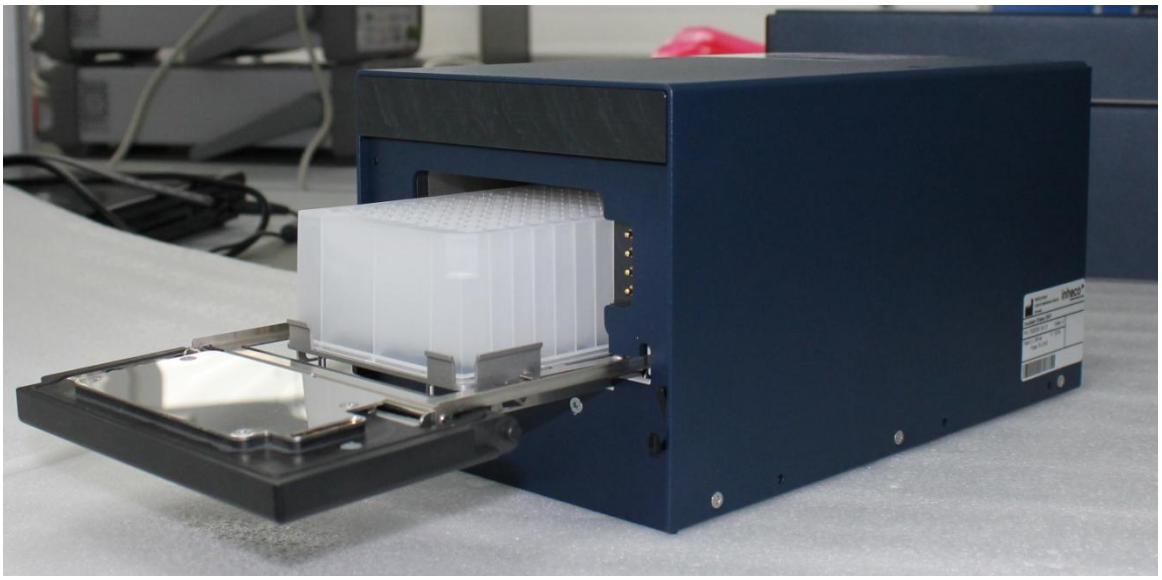
INHECO stackable devices

Incubator Shaker DWP

Part No.: 7300009
Document Nr: 900239-000

User's Manual



Important: The device has to be in a level position at all times, it may not be tilted or turned upside down, especially not when the transportation screws are not in place!

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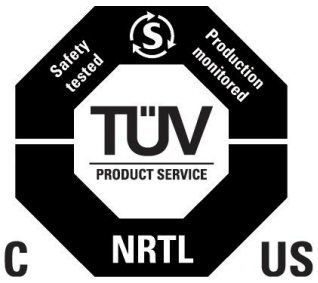
This manual belongs to

Type _____

Serial No. _____

Year of Manufacturing: _____

Order Confirming No. _____



To be filled in by customer:

Inventory No. _____

Place of installation _____

Important Notes

Read this manual carefully before using INHECO stackable devices.
In the following the names of the stackable devices, "Incubator Shaker" or "Incubator" are used. They represent one device of the "family" of stackable INHECO devices. Liability does not apply for mishandling the unit.

This manual is part of the Incubator Shaker and must be

- retained until the Incubator Shaker is disposed of.
- passed on to the new user when the Incubator Shaker is sold or lent.

Please contact the manufacturer in case you do not understand something within this manual.

Your opinion about this manual provides us with valuable insights on how we can serve you better. Please do not hesitate to direct your comments to us, using the address or the phone numbers on page 3.

Please read the safety instructions very carefully. They must be understood and observed in order to ensure safe handling of the unit.

Missing or insufficient knowledge of the manual leads to loss of liability against **INHECO**. The operator should therefore ask for an instruction confirmation from the manufacturer to ensure proper handling of the device.

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1. Explanation of Symbols and Abbreviations

A possible danger, leading to serious bodily harm is being pointed out to you.

Caution: hot surface

! A possible danger leading to less serious bodily harm is being pointed out to you. This signal also warns you of tangible damage.

A possibly dangerous situation leading to material damage is being pointed out to you.

Important!

This sign refers to useful information as to installation etc.

- Bullet points refer to enumeration.

These arrows indicate instructions.

■ The squares refer to procedures running automatically and the results to be achieved.

1.1. Abbreviations

The document uses the following terms:

CC: Communication controller
Controller: Microprocessor with on chip peripheral
CRC: cyclic redundancy Check
FCS: Firmware Command Set
Heater: Same as Temperature Controller
IVD(D): In vitro diagnostic (directive)
MP: Micro Plate
PCR: Polymerase Chain Reaction
PWM: Pulse-Width Modulation
Shaker: Controller for shaker regulation
TBC: To Be Continued
Temperature Controller: Controller for heat regulation
USB: Universal Serial Bus
CE: Conformity mark
NRTL: Nationally Recognized Testing Laboratory
DLL: Dynamic Link Library
PC: Personal Computer
EU: European union
SBS: Society for Biomolecular Screening
DWP: Deepwell Plate
IVD: In vitro diagnostics
FDA: Food and Drug Administration
DIP: Dual in line package

2. Safety Instructions

Avoid accidents. Always make sure that the unit is disconnected from the power supply system during any installation process.

Electric Shock Hazard

You can suffer an electric shock, if the unit is not connected properly or if you did not disconnect the unit from the power supply system before opening the housing.

Please observe the following measures in order to avoid muscle convulsions, burns, unconsciousness, apnea or even death:

⇒ Do not work with open housing when unit is connected to the power supply system.
⇒ Always switch off the unit before implementing any alterations. The power supply is operated at a voltage of up to AC 240V.

Burn Hazard

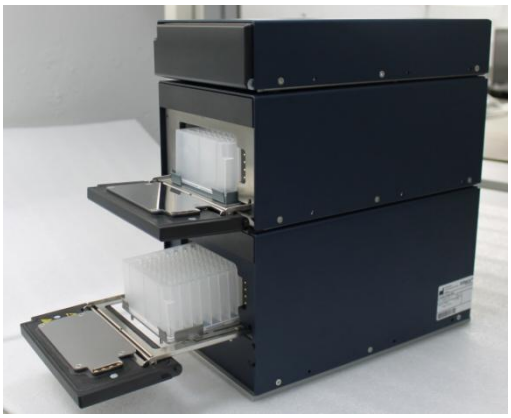
You can burn your skin when touching the inner parts and especially the microplate contact surface and disposables. These parts can reach up to 85°C (185°F)! Do not use materials that are not sufficiently temperature resistant up to 110°C (230°F).

Explosive, flammable and volatile materials may not be heated in the Incubator Shaker, at the risk of explosions!

3. Operating Instructions

3.1. Abstract

INHECO's compact single position Incubators are high performance plug & play devices for the use on automated robotic platforms or as standalone units.. They can either be used as single devices or stacked in a tower. In addition multiple towers or single devices can be controlled parallel from one host PC via USB. The combination of different devices of the Incubator family in one tower is possible.



Picture 1: Stacked Devices

The patented shaker design allows shaking of several different shaking patterns with high precision in frequency and amplitude.

The Incubators have built in safety features which enable them to be used in IVD and FDA applications (Technical Specification, chapter 5). The Temperature can be reported during processing to have a maximum of control. Precise temperature and shaker control, USB interface plate loading sensors and several self test routines guarantee a safe, precise and fast processing of probes.

The Incubator Shaker is a state-of-the-art device for incubating SBS listed micro plates including flat bottom and PCR (with adapter plate). Service support is guaranteed through INHECO.

3.2. Conventional Usage

The Incubator Shaker is a state-of-the-art device and complies with today's standards. The manufacturer attached much importance to the user's safety.

The following rules apply to the user:

- Rules of accident prevention
- General rules for technical safety
- EU and other country specific directives

The conventional usage contains the usage according to the manual.

You must be able to disconnect the main power supply to the instrument immediately if necessary.

An unimpeded air supply must be ensured to avoid injuries to persons and/or damage to the unit. Do not operate the Incubator Shaker DWP above the maximum ambient temperature to prevent the Incubator Shaker DWP from damage. Ensure that there is a minimum of at least 8cm (4 inches) free space at the rear ventilation openings.
The free space at the lower ventilation openings are accurately defined (3mm) by the positioning pins.

3.3. Who is permitted to operate this unit?

Only instructed and skilled persons are permitted to operate this unit. Only specialized staff is allowed to make any amendments to the operating menu.

3.4. Servicing the Incubator

Run the Command AQS every 100h (see Chapter 8).
Temperature calibration may be checked and repeated regularly.
Every 15000 operating hours or three years, whatever occurs first, an authorized INHECO service technician should be check the device.

Calibrate

INHECO recommends calibrating the Incubator device annually.

Cleaning

Before cleaning the Incubator Shaker DWP, disconnect the power and make sure that the temperature at the heating plate is below +50°C.
The contact surface should be cleaned regularly to ensure optimum heat transfer to the disposable. Always clean the contact surface if there has been a spillage. Use the cloth dipped in 50:50 water / isopropanol solution and make sure that no deposits are left on the surface. Care should be exercised to prevent water from running inside the unit.
Do not use aggressive cleaning fluids such as acetone, or abrasive cleaners.
Please check with INHECO any cleaning method that is not mentioned in it his paragraph to prevent damage to the Incubator Shaker DWP.

Decontamination

The most common decontamination method is by fumigation with formaldehyde or ethylene oxide gas.
The surface decontamination can include a wipe-down of the housing surface. A solution of 70% alcohol should be used where effective for target organisms
The use of Bleach (5%-12%) or Microside SQ is also possible.

Repair

The Incubator Shaker may only be repaired by authorized INHECO service technicians either locally or at INHECO's.

Shut down and Disposal

The unit is to be disposed in accordance with the environmental directives in effect in the respective country.

Caution!

The Incubator Shaker may only be operated in an upright and level position.

Important

The Incubator Shaker unit must not be stored below –10°C.

3.5. **Technical Alterations**

Important!

- Do not alter the product. For safety reasons no technical changes to this unit are allowed by unauthorized persons. Any modification or change, which is not approved by the manufacturer in written form leads to loss of warranty.
- The original parts are especially designed for the Incubator Shaker. Parts provided by other suppliers are not tested and therefore not approved by **INHECO**. Using such parts can impair the functionality of the unit and will lead to loss of warranty.
- For damages which may occur due to the usage of non original parts or non approved modifications or repairs, liability is excluded by **INHECO**.

3.6. **Malfunctions**

Report occurring malfunctions immediately to the responsible person named on page 3 of this manual.
Ensure that the unit is secured against violation and misuse.
Before the initial operation, dismantled safety relevant parts have to be mounted and checked.

3.7. **Name Plates and Labels**

Please check all name plates and labels and ensure that their legibility is maintained at all times during the life time of this unit.
Replace all name plates and labels if their legibility is no longer ensured.

4. Operating the Incubator Shaker DWP

4.1. Scope of Supply

Before initial operation, make sure that the shipment of your unit is complete and no parts are damaged. The following components should be included in each shipment:

1. Incubator Shaker unit
2. USB Cable between Incubator Shaker and PC
3. 15 pole SUB-D COM-Cable
4. CD or USB-Stick containing Manual and Software

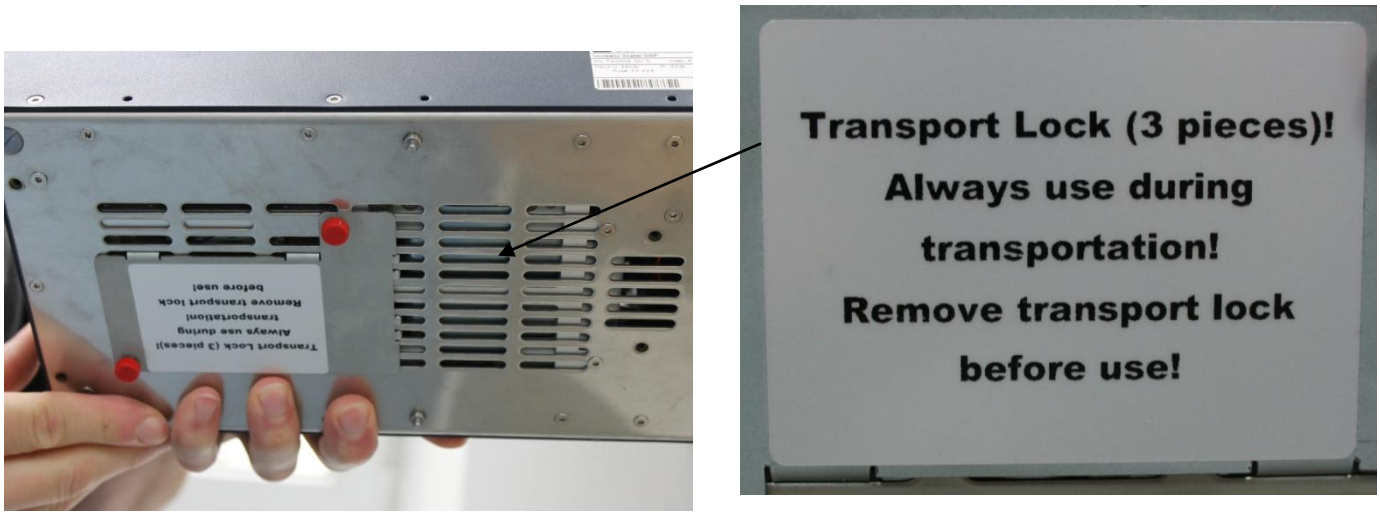
The Power Supply and Power Cable are not part of the scope of Supply, they have to be ordered separately (see chapter 12).

Picture 2: Scope of supply

4.2. Initial Operation

Transportation

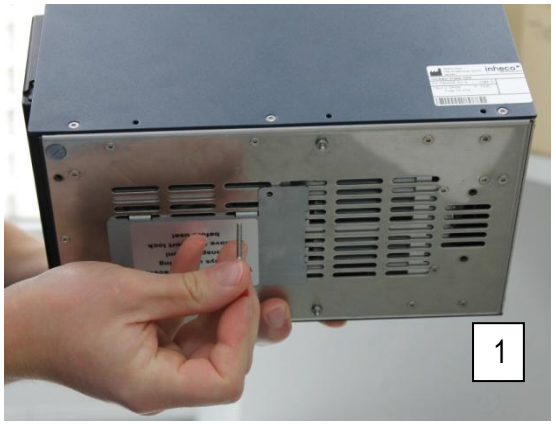
Picture 3: Transportation label at the upper side

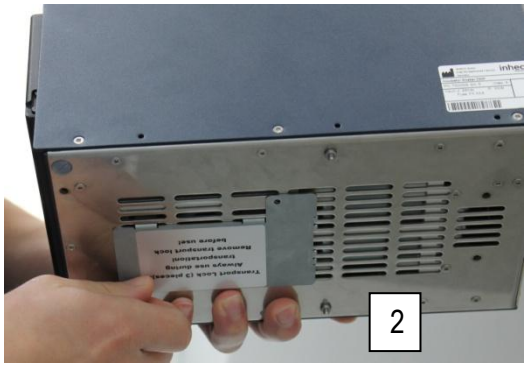


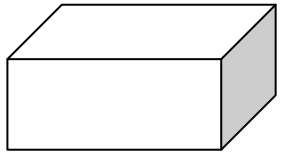
Picture 4: Transportation Lock at the bottom side

Assembling / disassembling of transportation lock!

Turn Incubator Shaker DWP slowly to the right (**Attention! – Cover side in direction of assembler, like in picture**)



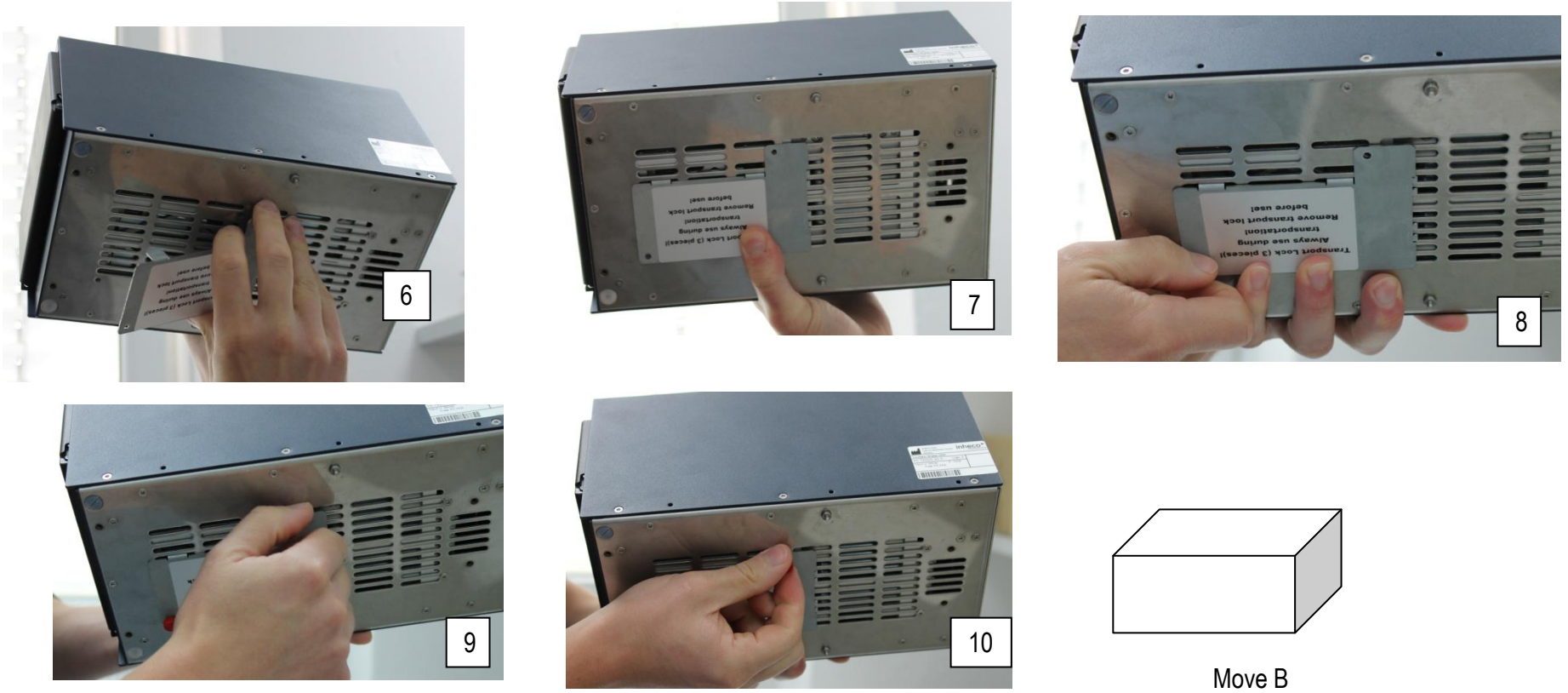




Move A

Picture 5: Assembling / disassembling of transportation lock (3 pieces)!

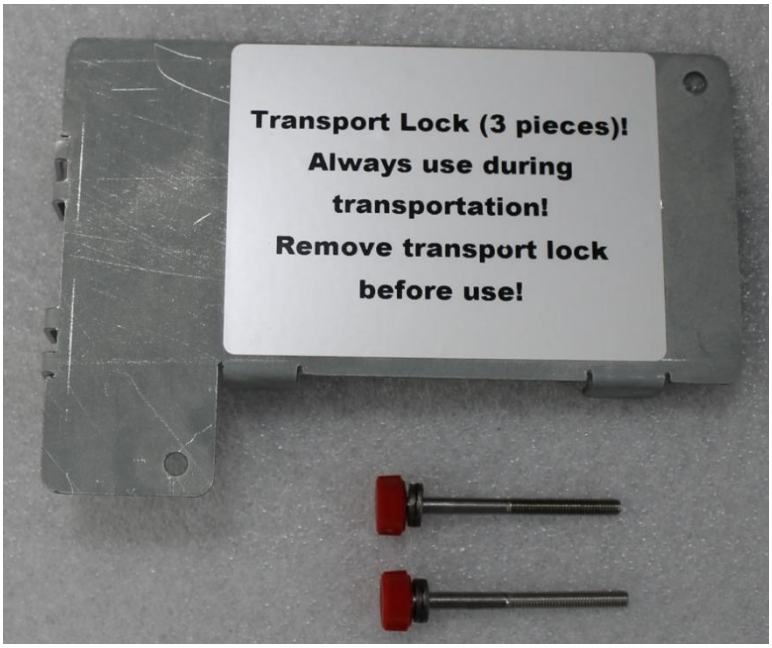
Turn Incubator Shaker DWP slowly to the left (**Attention! – Cover side in direction of assembler, like in picture**)



Picture 5.1: Assembling / disassembling of transportation lock (3 pieces)!

After unpacking the device, the two red screws (transportation lock) at the bottom side have to be unscrewed **without tilting or turning the device upside down**. Turning the unit upside down might require a renewal of the shaker drive calibration. Keep the screws for later transportation purposes. To install the transportation lock back again, don't turn the two screws too hard, just finger tight. Don't use a screwdriver! This could damage mechanical parts inside the device!
Do not dispose the original package, as it might be needed for further transportation.

Important: The device has to be in a level position at all times, it may not be tilted or turned upside down, especially not when the transportation screws are not in place!



Picture 6: red Screws

Mechanical Integration

Place the device on an appropriate plate for a firm and even stand. Use the position pins on the bottom side for exact positioning of the device/stack.
Important: It is not advisable to stack more than three devices on top of each other without additional mechanical fixation. Contact **INHECO** for more details.
Important: The plate/device has to be in balance for proper shaker performance.

Important: It is not advisable to stack more than one device on top of each other without additional mechanical fixation. Contact **INHECO** for more details.

With this method, it is possible to connect a maximum of two devices (one Master and one Slave).

The devices are built for the use with either deep well plates or microplates. The Labware detection is optimized for Nunc Plates. If different plates are used, the user has to assure, that the Labware detection works well with these plates too.

- Light master plates are better than dark ones
- Master plates with matt surface are better than shiny ones
- Attaching an adapted tape on the left side of the master plate improves the success rate of the Labware detection. With the command ASE1 the incubator shaker is unable to shake without detected Labware. The command ASEND has been added to enable shaking without detected Labware. We do not recommend using it! The command ASE1 is preferred. It ensures that the Labware is correctly placed on the shaker and performs within the specifications.

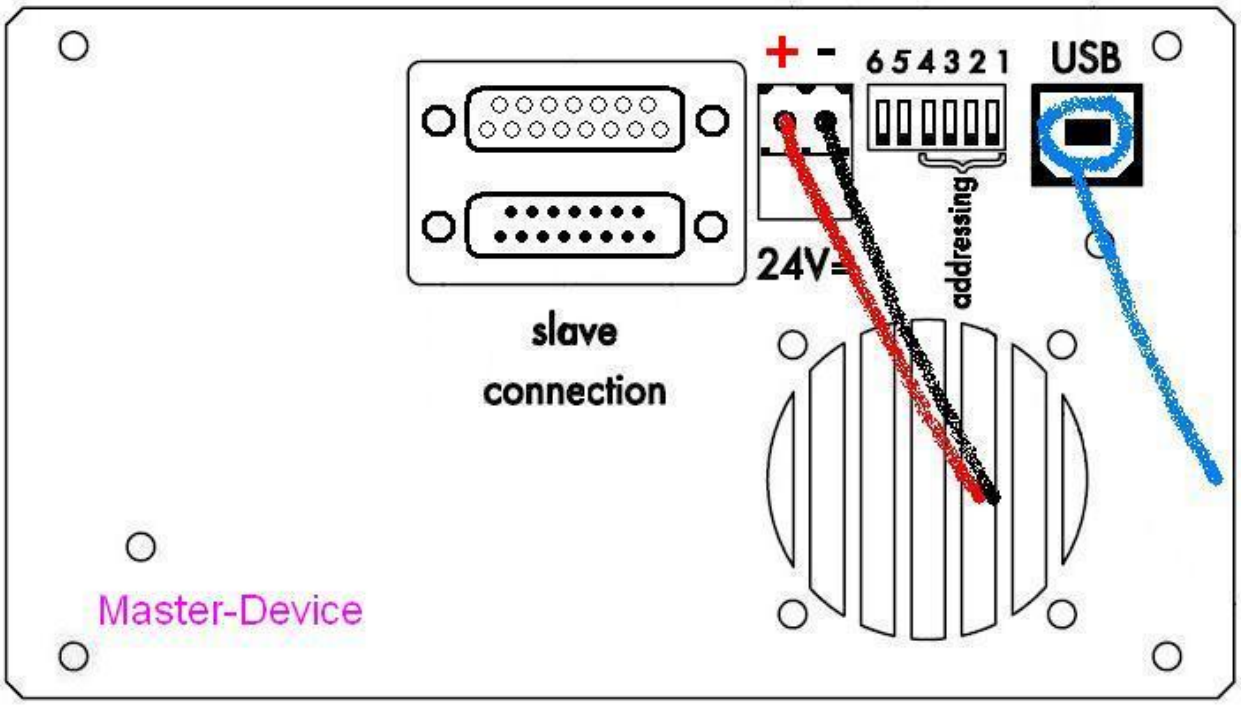
Important!

The bottom of the microplates must be flat to ensure uniform heat exchange. If the customer prefers plates with different shaped bottom, a special adapter is needed. **INHECO** offers to design and manufacture a customized adapter.
The devices can measure the temperature at the top of the heat plate only. The temperature of the liquid in the microplate differs from this. Therefore a heater offset must be defined and set before the temperatures in the liquid samples are correct (see also command SHO).
After Cmd AID for Initialization is send to the Incubator Shaker, the door will close, if it was open. If the door was already closed, a short buzzing sound can be heard.
When a microplate is put on the drawer and the door is being closed, the microplate will be clamped on the drawer. When the drawer reaches its end position inside the Incubator Shaker, the microplate will be sinking on the heat plate for best thermal contact. You can hear a short shaking noise to ensure, that the microplate is sinking on the heat plate but only when the microplate is detected correctly from the device.
The heat plate has three integrated sensors for measuring the temperature. The temperature of the sensors is averaged.

Electrical Details General

The device needs an electrical power supply that provides a stable 24Vdc voltage. The power consumption for one device is max. 2,7 Ampere (65 Watt). If more devices are stacked, the power supply must be able to deliver the resulting power consumption. The polarisation at the power connector at the back side is shown in the following picture. The red wire symbols the “plus-pole” and the black the “minus-pole”.

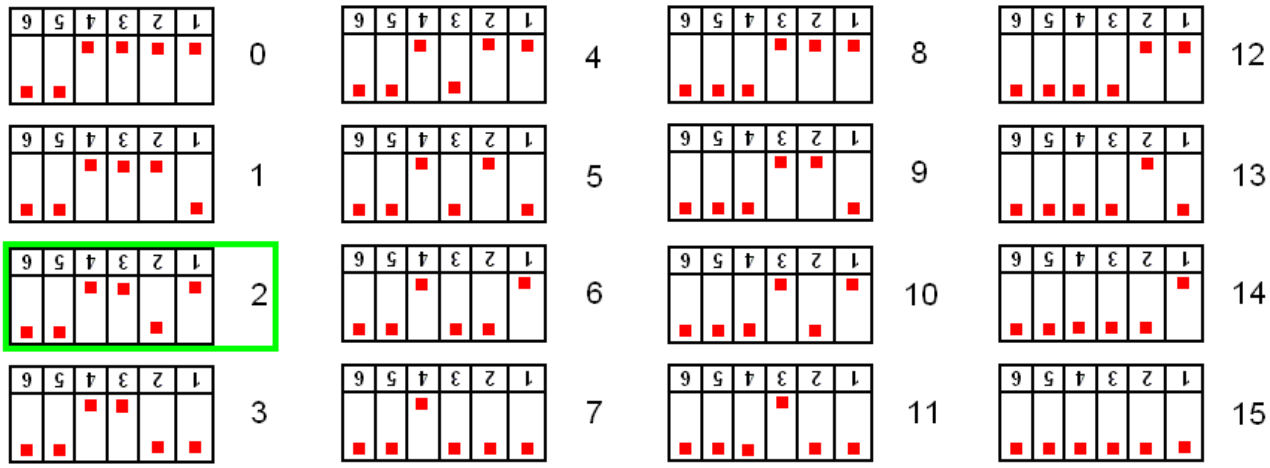
To communicate with the device, a computer with an USB-Connection is necessary. The USB-Connector is placed at the back side (see blue mark at picture 8).



Picture 8: Standard connection for one device

Address-Switch

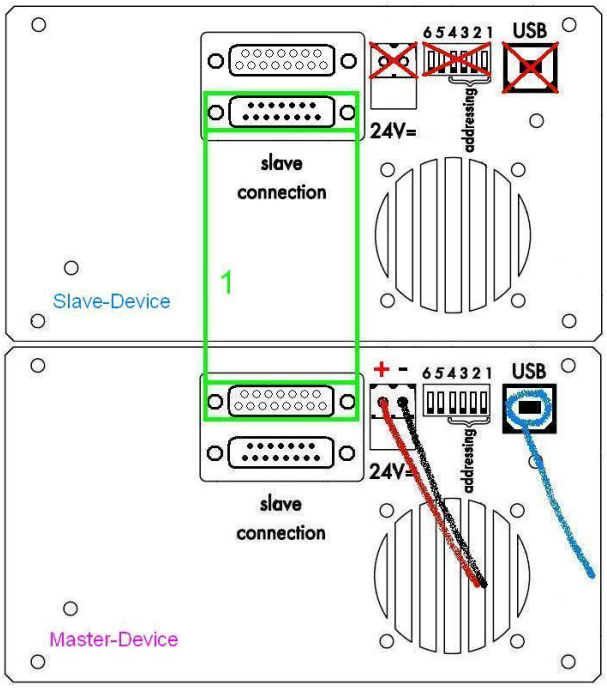
A six-pole DIP-Switch can be found at the back side. Only the switches 1 to 4 are used for setting the address. These switches are for identification, if more than one single-device or stack is connected to the PC. The default address is “2”. The recognition of the device/stack depends on the switches position as shown in picture 9.



Picture 9: Address-Switch

Connecting Devices

Two devices are operated with one power supply and controlled via one USB interface, the 15-pole SUB-D-Connectors on the back side are used. The following pictures show, how the devices have to be connected. When placing the device at its desired position, make sure that the fan on the back side has at least 3 cm space to the wall to ensure proper airflow!



Picture 10: two connected devices

4.3. USB Communication

Hard- and software features of the Incubator USB virtual COM port are specified in this section.

Remark: The USB is not optimized for secure real time data transfer. Therefore all communication is secured by a cyclic redundancy checksum (crc). If the communication between the PC and the MTC does often fail or results in timeouts, in most cases the PC is causing the problem. . Therefore we recommend for a robust communication the following:

1. Other devices connected to the USB might have an influence on the communication stability of the incubator
2. Use a simple workstation PC
3. The stability of the communication has to be verified with every PC
4. Windows 7 and Vista seems to be more stable than Windows XP
5. Do not activate the automated update from Windows

4.4. Communication of Incubators to the USB Host PC

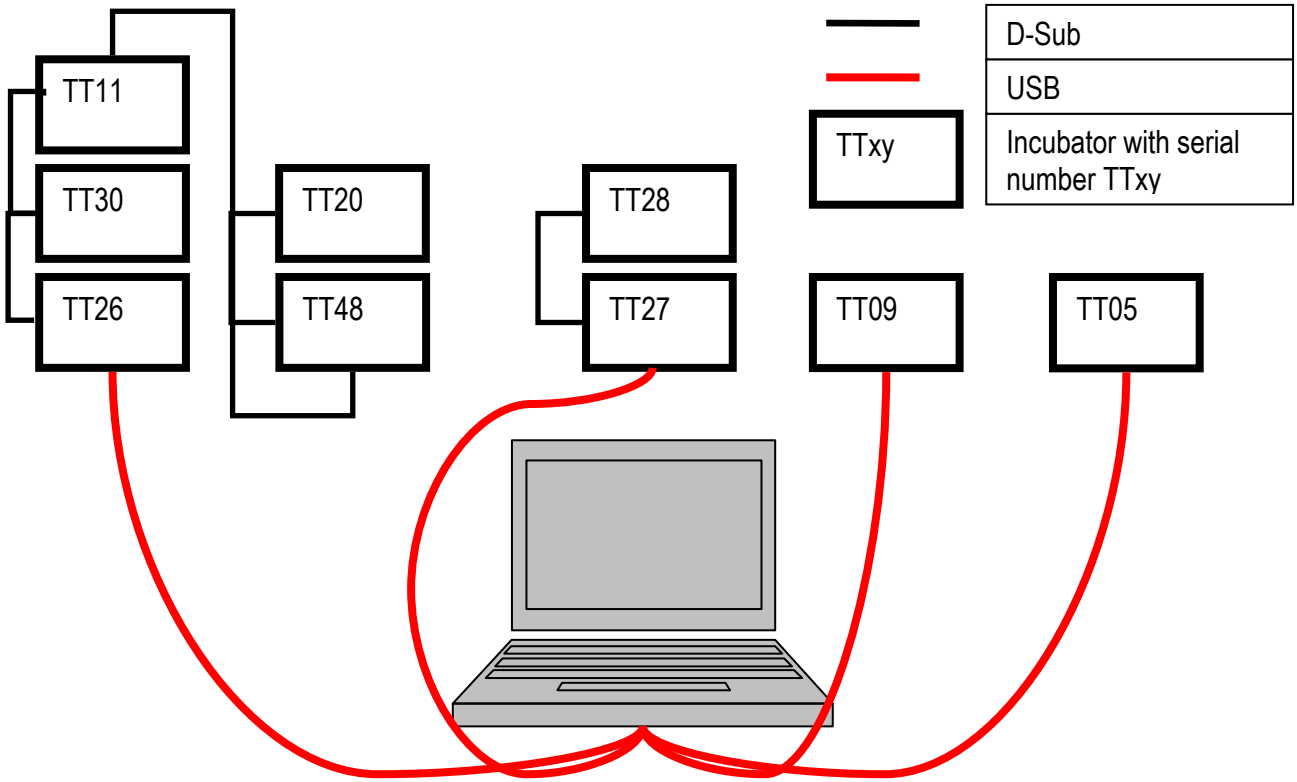
Our recommendation for Incubator Shakers is to use it in three floor stacks. For details see section 4.2. For the example on hand we want to use a more complicated configuration:

- Five devices daisy chained with the D-Sub-D connectors (Two power supplies are needed, one for two and one for three devices).
- Two devices in one stack
- One single device
- A second single device

The LED indicates the status of the module:

- Power on and device is initialised >> LED on
- Firmware download >> LED is blinking (ca. 3-5 Hz)
- USB-Communication not present >> LED is blinking (ca. 1 Hz)

Details shown in the picture below



Picture 18: Interconnection

The starting basis is as follows:

1. USB drivers installed on the PC
2. The PC is connected to the bottom Incubator of a stack via USB.
3. The INHECO tool is installed on the PC
4. All COM ports are closed.
5. All Incubators are daisy chained power is switched on on and they are connected to the PC.

After pushing the button “Find Incubators @ COM Ports”, all COM Ports will be scanned and some commands of the Firmware Command Set will be automatically executed to determine the configuration. The results will be written into the textbox of the tool and the combo boxes for COM port and device ID will be set respectively. In more detail:

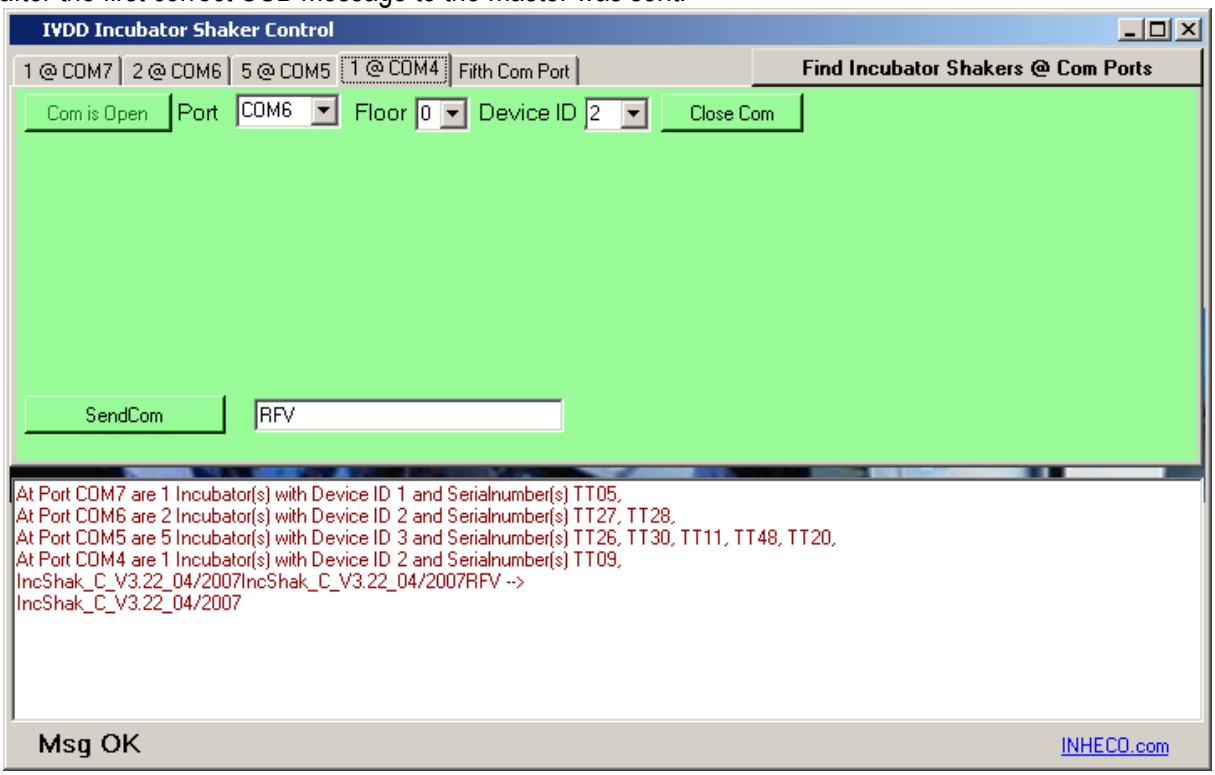
6. Find out all available COM ports[1].
7. Open next available COM port. If none go to 18.
8. Send an arbitrary command for “synchronisation and announcement”.
9. If no reply → Close COM port and go to 7.
10. Else (important): Look if a device ID error is present and look at the reply (this is working since firmware version CC 3.17).
11. → Device ID of that stack (master device).

[1] If you have used for example a USB Bluetooth adapter on your PC, Windows sometimes creates lots of COM ports for this purpose. If you plan to use that PC to control Incubators we recommend deleting all these COM ports first.

12. Send RDA0,1 to the master on this COM Port with the device ID found.
13. → Number of floors (# Slave devices).
14. Send RFV2 to the master and all its slave devices (take care of the floor ID, T00 → T01 → T02 …) up to the number of slave devices.
15. Store serial numbers, COM port name, number of devices and device ID.
16. Close the COM port.
17. Go to 7.
18. Write the results to the textbox and fill the combo boxes of device ID and COM port name and the tabs accordingly.
19. Finished (see picture 16 for the result).

Now you are able to open four COM ports. Just click at Open COM on the four tabs.

For the implementation it is important to consider different setup conditions. Some devices may be already connected to the USB (green LED is on) some may not (green LED is blinking at 1 Hz). The blinking of the LED stops only after the first message with the correct device ID is sent to the Incubator device. Therefore you need to send at least two messages to bring all devices into the same state. The reason for that is that slave devices have to register themselves to the master device within a certain time frame. This happens after the first correct USB message to the master was sent.


IVDD Incubator Shaker Control
1 @ COM7
2 @ COM6
5 @ COM5
1 @ COM4
Fifth Com Port
Find Incubator Shakers @ Com Ports
Com is Open
Port
COM6
Floor
0
Device ID
2
Close Com
SendCom
RFV
At Port COM7 are 1 Incubator(s) with Device ID 1 and Serialnumber(s) TT05,
At Port COM6 are 2 Incubator(s) with Device ID 2 and Serialnumber(s) TT27, TT28,
At Port COM5 are 5 Incubator(s) with Device ID 3 and Serialnumber(s) TT26, TT30, TT11, TT48, TT20,
At Port COM4 are 1 Incubator(s) with Device ID 2 and Serialnumber(s) TT09,
IncShak_C_V3.22_04/2007IncShak_C_V3.22_04/2007RFV -->
IncShak_C_V3.22_04/2007
Msg OK
INHECO.com
Picture 20: Application Example

- The COM ports may change therefore pleas use the device ID to have a unique identification of a stack.
- Parallel communication to different COM ports is possible.
- Parallel communication with different members of one stack is forbidden and may result in errors.

4.5. Commands

All commands for the integration of the single Incubator are described in the document “Incubator FCS /Document NR: 900334-XXX”.

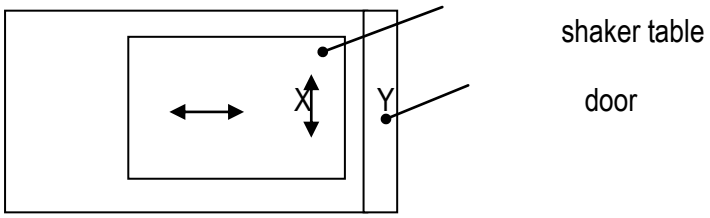
5. Technical Specifications

5.1. Technical Data

Incubator Shaker	Technical Data
Limits for ambient operating temperature	+15°C to +30°C [+59°F to +86°F]
Input voltage	24Vdc
Input current (Power)	4A (60W) max.
Temperature range	Room Temperature plus 5K to +80°C [+176°F]
Tolerable relative humidity ambient	10-80% relative (non condensing) at +30°C [+86°F] or below
Maximum load of the shaker platform	0,25 kg
Shaker frequency range	6,6 Hz to 30 Hz → 400 rpm to 1800 rpm
Maximum shaking amplitude	3 mm (difference between the maxima)
Shaking direction	Arbitrary
Storage conditions	-10°C to +60°C [+14°F to +140°F], non condensing
Length x Width x Height	See chapter 5.4
Weight including cables	5,7 kg
# of devices in one stack	Maximum two due to interaction during shaking

5.2. Shaker Functionality

Parameter	Value
Amplitude range	0.0 – 3.0 mm* * For detailed shaker performance, see chapter below.
Speed range	6.6 – 30.0 Hz* * For detailed shaker performance, see chapter below.
Speed precision	±2 Hz
Load	(weight of plate and liquid and adapter) 40 – 250g* * For detailed shaker performance, see chapter below.
Supervision	speed and amplitude (closed loop controller)
Shaker movement	North – South East – West Round “Eight”
Shaker movement	Amplitude accuracy** ±20% (of the target amplitude) Phase shift accuracy** ±11° ** validated for the Heating Plate movement / average value over 10 cycles

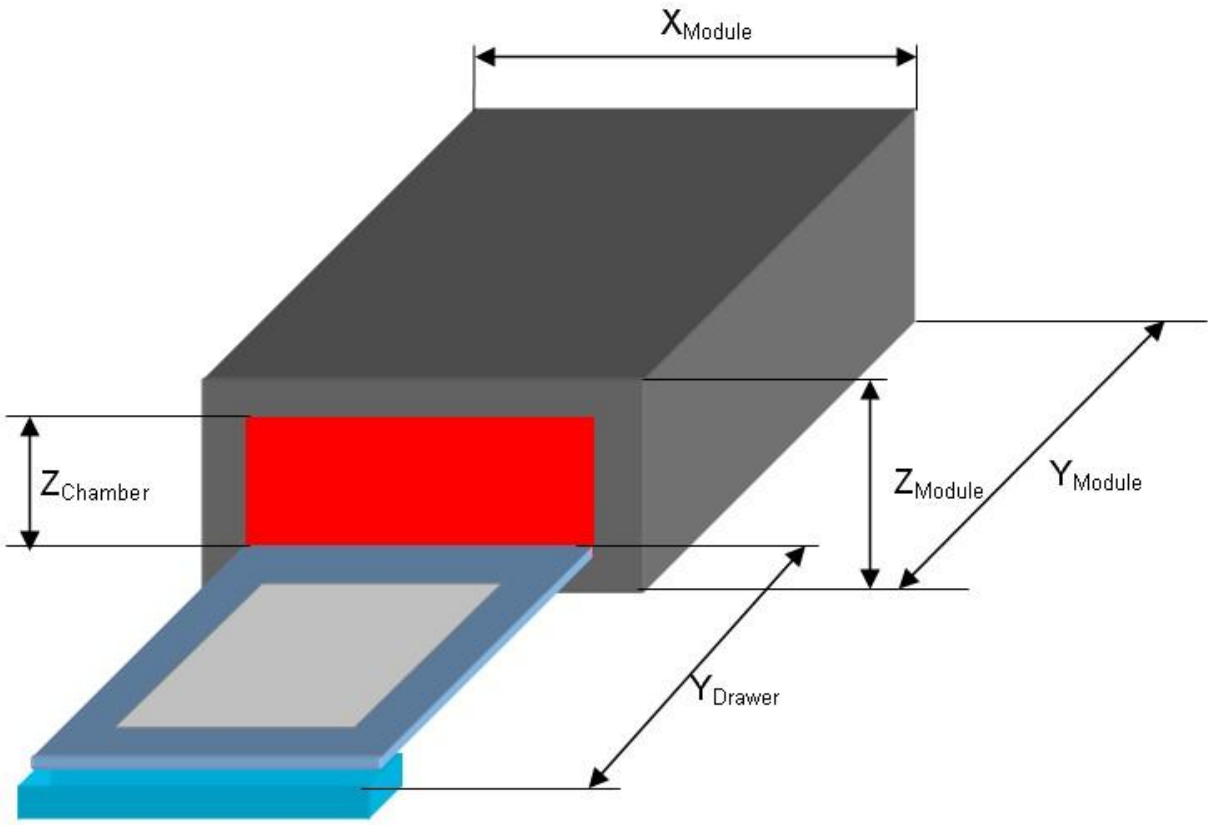
	Single Axis (North – South and East – West)		Shaker Load: 100g
	Shaker Speed [Hz]	Shaker amplitude [mm]	
		Single Device	Triple Stack
	10	X = 1.0 to 2.2 or Y = 1.0 to 2.2	X = 1,0 to 1.9 or Y = 1.0 to 1.9
	15	X = 1.0 to 2.7 or Y = 1.0 to 2.7	X = 1.0 to 2.4 or Y = 1,0 to 2.4
	20	X = 1,0 to 1.2 or Y = 1.0 to 1.2	X = 1.0 to 1.2 or Y= 1.0 to 1.2
	Round (Phase shift = 90°)		Shaker Load: 100g
	Shaker Speed [Hz]	Shaker amplitude [mm]	
		Single Device	Triple Stack
	10	X = 1.0 to 2.2 Y = 1.0 to 2.2	X = 1,0 to 1.9 Y = 1.0 to 1.9
	15	X = 1.0 to 2.7 Y = 1.0 to 2.7	X = 1.0 to 2.4 Y = 1.0 to 2.4
	20	X = 1.0 to 1.2 Y = 1.0 to 1.2	X = 1.0 to 1.2 Y = 1.0 to 1.2
			

5.3. Thermal Functionality

Parameter	Value
Temperature range	Room Temperature plus 5K to +80°C [+176°F]
Accuracy absolute (@ ambient temperature stability ±1K)	The accuracy is defined as the difference between the target temperature of the heating plate and the average of the measured temperature on the heating plate. The heating plate temperature is measured at 5 positions on the heating plate according to the Special INHECO measurement head PM-0105. The 5 measurement positions are according to the Plate positions A1,

<table>
<tr><td></td><td colspan="2">H1, E6, A12 and H12.</td></tr>
<tr><td></td><td>Target Temp. Validation Tool</td><td>Accuracy [°C]</td></tr>
<tr><td></td><td>+37°C [+98,6°F]</td><td>±1</td></tr>
<tr><td></td><td>+60°C [+140°F]</td><td>±1.5</td></tr>
<tr><td></td><td>+80°C [+176°F]</td><td>±2</td></tr>
<tr><td>Uniformity measured in well</td><td colspan="2">Uniformity is defined by the maximum difference between lowest and highest temperature according to a Nunc 96 Round Bottom (A1, A12, E7, H12)</td></tr>
<tr><td></td><td>Target Temp. Validation Tool</td><td>Uniformity [°C]</td></tr>
<tr><td></td><td>+37°C [+98,6°F]</td><td>±0.8</td></tr>
<tr><td></td><td>+60°C [+140°F]</td><td>±1.2</td></tr>
<tr><td>Evaporation in unsealed Micro Plates</td><td colspan="2">Incubator temperature +37°C [+98,6°F], max. 10% loss of liquid in 4 h, deionized water, room temperature 24-26°C [75,2-78,8°F], rel. humidity 40-50%, altitude at 410 m over Sea level
If there are problems with extreme condensation, the functionality of the upper heating foil might be no longer given. Check the performance of the upper heating foil by reading out the temperature with the commands RAV5, RAV6, RAV7 RAV8 at ambient temperature. Record the values. Heat the Incubator five minutes at 80 ° C and then read out the values again. The values should be decreased by four points, if the upper heating foil is working within specifications.</td></tr>
<tr><td>Heatup time</td><td colspan="2">Start temperature +15.6°C [+60°F]; Target temperature +37 °C [+98,6°F]; Heat up time max.100 min; Volume 1,5ml per well. The target temperature is reached when all sensors are in the tolerance band of 37°C ±1°C [98,6°F ±3,6°F]
Measured with:
1) NUNC 96 Deep Well Plate</td></tr>
</table>

5.4. Module Dimensions, Weight



Picture 21: Dimensions

5.4.1 Dimensions and Weight

Parameter	Value
Dimension in X_{Module}	149 mm
Dimension in Y_{Module}	1) 268,5 mm without connector cables 2) 298,5 mm with connector cables
Dimension in Z_{Module} (without pin)	139 mm
Open drawer incl. door Y_{Drawer}	209 mm
Dimension of thermal chamber in $Z_{Chamber}$	49 mm
Weight (without cables)	5,4 kg

5.4.2 Drawer Specifications

Parameter	Value
Accuracy of the end position of the drawer in x, y and z (drawer open); single unit, all parts at specified ambient temperature	±0,30 mm
Maximum Drawer load	0,25 kg
Open drawer resistance for a force in Z-axis without plastic deformation	10 N

6. Final QS Tests

All units, which leave INHECO, have to pass through three semi-automatic test procedures.

6.1. Drawer Test

The device must pass at least 100 drawer cycles with correct Labware detection without error.

6.2. Performance Test

Finally all important functions are tested and the self test AQS (see chapter 8) must run without error.

7. Calibration and Adjustment

The adjustment of the shaker and/or the calibration of the temperature are done at INHECO. Settings are stored into the devices EEPROMS and redundant in an INHECO Database. A redundant check of all data is done.

8. Automatically self test AQS

The automatically self test AQS is performing several tests to ensure proper functionality of the device. After the tests are finished, the device generates an error code (see Firmware Command Set). These tests are:

- Drawer Test: Checks opening and closing of the drawer.
- Shaker Test: Tests timing, amplitudes and frequencies of different settings
- Temperature Test: Tests timing and homogeneity of the heating procedure including boost.
- Duration: 3 min. 30 sec.

9. Detailed description of the Error Codes

The error codes embedded into the message reply are mainly meant to give the user additional information about the status of the device. The reply to every command ends always with the following three hex data:
0xB0+device ID:

This ensures that it is a reply from the device with this device ID.

0x20-error code:

The following table 1 describes the error codes (see also Firmware Command Set):

Table 1: error codes

Code	***Error message***	***Detailed description***
0	Message Ok	Normal return message.
1	Reset detected	Power on, software or watchdog reset. Three kinds of resets are possible: i) Power on reset → after the first ordinary message reply after power on this error code will be send. This is a correct behaviour ii) Software reset → after the command SRS the green led in front of the device blinks shortly. The software reset brings the device into the same state after power on. Therefore also here this error code will be send. iii) Watchdog reset → if the firmware runs into trouble in most imaginable situations a watchdog reset occurs. This error code will be send. Please inform the INHECO Tec-hotline in such a case.
2	Invalid command	The Command does not exist for this device. This flag is set if the command is completely unknown. E.G if a shaker command has been sent to an Incubator without shaker function.
3	Invalid operand	Parameter out of range (see command set). This error code will be reported, if the Parameter of a correct command is out of range. E.G. SAX307
4	Protocol error	USB Protocol error. Wrong message length or CRC. The USB Message is secured by a cyclic redundancy check at the last byte of a message. If the last byte is incorrect or missing this error code will be reported.
5	Timeout from device	Device did not answer within the expected time frame. This error must be generated by the PC application
6	Device ID error	The device ID can be changed at the dip switch on the rear side of the device. If the message one sends to this device has the wrong device ID this error is replied.
7	Device not initialized	Command requires prior initialization of a sub system. E.g. It is not possible to open the drawer or to shake the Labware of a non initialised device.
8	Command not executable	Parameter or device condition prohibits execution. The typical example is that no Labware has been detected and the user tries to shake using the command ASE1.
9	Drawer not in end position	The drawer is in an unknown position (generated by RDS). E.G. the door is blocked
10	Unexpected Labware Status	A Labware is detected on AOD after a power-up or after an undefined drawer status.
11	Reserved	-
12	Reserved	-
13	Drawer DWP not perfectly closed	NTC resistor not connected – check drawer
14	Floor ID error	Device is not registered in the master. E.G. A command has been send to the slave device with ID 2, but only one slave is connected to the master.
15	Timeout sub device	The error message is from this device. The sub devices, heater or shaker did not answer within the expected time frame. The Incubator Shaker has three µCs. The heater and the shaker controller work as a kind of sub devices of the communication controller. If the inter µC communication is corrupted this error code will be reported.

Most error codes can be used for a PC lab automation application to generate its own error codes or to change automatically its operation status. E.G. if the device ID error is reported the device ID must be changed.

Ox60:

End of reply

10. Typical process example

A typical cycle for a process should contain the following steps:

- Scan COM Ports
- Find device ID, # slaves and serial number of all connected devices
- Check the number of drawer cycles and the firmware versions of all devices
- Initialize all devices
- Open doors simultaneous or sequential
- Put in the Labware and the adapter if necessary
- Set target temperature for each Incubator
- Set heater offset according to the used type of micro plate
- Set frequencies, amplitudes and phase shift for all devices
- Close the doors
- Start shaking
- Start heating
- Check cyclic temperatures, frequencies, amplitudes and the error flags
- Optional change target temperature
- Optional restart heating
- Optional change frequencies etc.
- Optional restart shaking
- Stop shaking and heating
- Open all doors

11. Warranty

2 Years from date of shipment. Any damage by abuse or caused by operation different from this instruction is not covered.

12. Power Supplies

The Power Supplies can be ordered separately at INHECO.

Picture 22: Power Supply built for 1 and more incubators

Power Supply built for 1 and more incubators
AC Input: 100-240V / 2,5A / 50-60 Hz
DC Output: 24V / 7,5A
Part #: 2400121

Picture 23: U.K. Power Supply Cord set
Part #: 1004214

Picture 24: European Power Supply Cord set
Part #: 1004184

Picture 25: North-American Power Supply Cord set
Part #: 1004185

Table 2: Version Management

VERSION NO	RELEASE DATE	CHANGES TO PRIOR VERSION
1.0	May2012	-

1. Declaration of Conformity

INHECO GmbH
82152 Martinsried
Germany

Declares that the following product:

Incubator Shaker DWP

Meets the essential requirements of the following European Union Directive(s) using the relevant section(s) of the normalized standards and related documents shown:

Standard and Date of Issue	
IEC 61010 – 1 : 2001 (2nd Edition) EN 61010 – 1 : 2001 (2nd Edition)	Safety requirement for electrical equipment for measurement, control and laboratory use.
EN 61010-2-010: 2004	Particular requirements for laboratory equipment for the heating of materials.
EN 61000-3-2 EN 61000-3-3	Electrical equipment for measurement, control and laboratory use. EMC requirements.
EN 61326-1: 2006	Electrical equipment for measurement, control and laboratory use. EMC requirements.

This product is in complies with the essential requirements of the Low Voltage Directive 73/23/EWG and
EMC directive 2004/108/EC, when used for its intended purpose.

Place	*Martinsried/ Munich*
Date	*May 2012*
Signature	
Name, Position	*Günter Tenzler, Managing Director*